DAVYDOV Michel

Introduction

Well-posedness c limit SDEs

Convergence in a toy model

References

# An introduction to mean field theory

DAVYDOV Michel

November 25th 2020

DAVYDOV Michel

Introduction

Well-posedness o limit SDEs

Convergence in a toy model

References

## Object of study

Object of interest= evolution in time of a system of interacting particles. Particles= very wide meaning (neurons, queues, players,...)

> DAVYDOV Michel

Introduction

Well-posedness o limit SDEs

Convergence in a toy model

References

#### Microscopic approach

Describing the behavior of the system through a system of SDEs

#### Example

Let  $N \ge 1$ . We consider the stochastic processes  $X^{k,N}$  on  $\mathbb{R}$  for  $1 \le k \le N$ , verifying the SDEs

$$X^{k,N}(t) = X^{k,N}(0) + \omega^k(t) + \int_0^t \frac{1}{N} \sum_{j=1}^N b(X^{k,N}(s), X^{j,N}(s)) \, \mathrm{d}s \ \ (1)$$

where  $\omega^k$  are independent BM, and b is a globally Lipschitz function.

DAVYDO\ Michel

Introduction

Well-posedness c limit SDEs

Convergence in a toy model

References

#### Example

Let  $N \ge 1$ . We consider the stochastic processes  $X^{k,N}$  on  $\mathbb{R}$  for  $1 \le k \le N$ , verifying the SDEs

$$X^{k,N}(t)=X^{k,N}(0)+\omega^k(t)+\int_0^trac{1}{N}\sum_{j=1}^Nb(X^{k,N}(s),X^{j,N}(s))\,\mathrm{d}s$$

where  $\omega^k$  are independent BM, and b is a globally Lipschitz function.

## A few remarks

- Without the noise, just a set of ordinary ODEs.
- We have existence and trajectorial uniqueness of the solutions (stochastic Cauchy-Lipschitz theorem).
- Good modelization, but hard to compute.

> DAVYDOV Michel

Introduction

Well-posedness o limit SDEs

Convergence in a toy model

References

## Macroscopic approach

Describing the behavior of a simplified version of the initial system through a system of SDEs that are no longer interlocked and that describe the statistical distribution of the particles.

## Example

We consider the stochastic processes  $\overline{X}^k$  on  $\mathbb{R}$  for  $1 \le k \le N$ , verifying the SDEs

$$\overline{X}^{k}(t) = \overline{X}^{k}(0) + \omega^{k}(t) + \int_{0}^{t} \int_{\mathbb{R}} b(\overline{X}^{k}(s), y) \mu_{s}^{k}(\mathrm{d}y) \,\mathrm{d}s, \quad (2)$$

where  $\omega^k$  are independent BM, *b* globally Lipschitz function and  $\mu_s^k$  is the law of  $\overline{X}^k(s)$ .

> DAVYDOV Michel

Introduction

Well-posedness c limit SDEs

Convergence in a toy model

References

## A few remarks

- Infinite number of particles— > statistical approach (sometimes called thermodynamic limit)
- Heuristic: equation (2) is intuitively what we believe the limit of (1) verifies when N goes to infinity (law of large numbers)
- We obtain nonlinear SDEs, but they don't depend on each other anymore- > asymptotic independence
- Information lost compared to the initial model (correlations between particles for example, or finite size effects).

DAVYDOV Michel

Introduction

Well-posedness of limit SDEs

Convergence in a toy model

References

## Putting the "mean-field" in "mean-field theory"

Note that we can rewrite (1) in terms of its empirical mean measure:

$$X^{k,N}(t) = X^{k,N}(0) + \omega^k(t) + \int_0^t \int_{\mathbb{R}} b(X^{k,N}(s), z) e_s^N(\mathrm{d}z) \,\mathrm{d}s,$$
 (3)

where for all  $r \ge 0$ ,  $e_r^N = \frac{1}{N} \sum_{j=1}^N \delta_{X_r^{j,N}}$ .

## Remarks

- We are interested in the convergence in law of this empirical measure when *N* goes to infinity. If it converges, there is asymptotic independence and this is called propagation of chaos.
- We have exchangeability, that is, invariance by permutation of the law of (X<sup>1,N</sup>,...,X<sup>N,N</sup>).

> DAVYDOV Michel

Introduction

Well-posedness or limit SDEs

Convergence in a toy model

References

#### The results

- Well-posedness of the SDEs (2).
- Convergence in probability of the empirical mean measure on the space of probability measures on the space of trajectories.

## Aim of the talk

- Discuss the general techniques used to prove the first type of results.
- Present the convergence of (1) to (2) on a simple toy model using coupling techniques.

> DAVYDOV Michel

Introduction

Well-posedness o limit SDEs

Convergence in a toy model

References

## Well-posedness of limit SDEs

Two main techniques: probabilistic and analytical (we won't discuss the second one here)

#### Probabilistic approach

- Define the "right" distance on the space of probability measures on the space of trajectories
- Introduce a function Φ on this space that associates to a measure the law of the solution to a linearized version of the SDEs (more detail on this later)
- Show that this function  $\Phi$  has a unique fixed point.

> DAVYDO\ Michel

Introduction

Well-posedness of limit SDEs

Convergence in a toy model

References

#### Wasserstein distance for continuous trajectories

Let  $\mu$  and  $\nu$  be two probability measures on  $\mathcal{C} = C([0, T], \mathbb{R}^N)$ . We define the Wasserstein distance between them by

$$\mathcal{D}_{\mathcal{T}}(\mu,\nu) = \inf_{\Pi} \{ \int_{\mathcal{C}\times\mathcal{C}} \sup_{s\in[0,T]} |\omega^{1}(s) - \omega^{2}(s)| \wedge 1 \,\mathrm{d}\Pi(\omega^{1},\omega^{2}) \}, \quad (4)$$

where  $\Pi$  probability measure on  $\mathcal{C} \times \mathcal{C}$  such that its first marginal is  $\mu$  and its second is  $\nu$  ( $\Pi$  is called a coupling of  $\mu$  and  $\nu$ ).

### Properties

- $D_T$  is a distance on  $\mathcal{P}(\mathcal{C})$ .
- $(\mathcal{P}(\mathcal{C}), D_T)$  is a complete metric space
- $D_T$  is nondecreasing in T.

> DAVYDOV Michel

#### Introduction

Well-posedness limit SDEs

Convergence in a toy model

References

## The linearized SDE

Let  $\Phi : \mathcal{P}(\mathcal{C}) \to \mathcal{P}(\mathcal{C})$  such that for all  $m, \Phi(m)$  is the law of the solution of the SDE on  $\mathbb{R}^N$ :

$$Z(t) = \overline{X}(0) + B(t) + \int_0^t \int_{\mathbb{R}^N} b(Z(s), y) m(\mathrm{d}y) \,\mathrm{d}s,$$

## The original SDE for reference

$$\overline{X}(t) = \overline{X}(0) + B(t) + \int_0^t \int_{\mathbb{R}^N} b(\overline{X}(s), y) \mu_s(\mathrm{d}y) \,\mathrm{d}s,$$

with  $\mu_s$  is the law of  $\overline{X}(s)$ .

> DAVYDOV Michel

#### Introduction

Well-posedness o limit SDEs

Convergence in a toy model

References

#### Main result

 $\Phi$  has a unique fixed point.

#### Idea of proof

- Show that  $D_t(\Phi(\mu), \Phi(\nu)) \leq C_t \int_0^t D_s(\mu, \nu) \, \mathrm{d}s$ . (uses Gronwall's lemma)
- Show a similar bound for iterations of  $\Phi$ .
- Conclude that (Φ<sup>n</sup>(μ))<sub>n</sub> is a Cauchy sequence, from which it follows that its limit is a fixed point of Φ.

DAVYDOV Michel

Introduction

Well-posedness o limit SDEs

Convergence in a toy model

References

## Consequence

• Existence and uniqueness (in law and trajectorial) of the solution to (2)

DAVYDOV Michel

Introduction

Well-posedness c limit SDEs

Convergence in a toy model

References

## A toy model for proving convergence

To simplify calculations, let us consider the initial model with the function b(x, y) = x - y. We then have the following SDEs:

$$X^{k,N}(t) = X^{k,N}(0) + \omega^{k}(t) + \int_{0}^{t} (X^{k,N}(s) - \frac{1}{N} \sum_{j=1}^{N} X^{j,N}(s)) \, \mathrm{d}s$$
 (5)

where  $\omega^k$  are independent BM.

## Remarks

- The SDE is now linear
- Disregarding the noise, there is exponential convergence to the mean position of the particles.

> DAVYDOV Michel

Introduction

Well-posedness c limit SDEs

Convergence in a toy model

References

### The new intuitive limit process

The limit process now verifies the following SDE:

$$\overline{X}^{k}(t) = \overline{X}^{k}(0) + \omega^{k}(t) + \int_{0}^{t} (\overline{X}^{k}(s) - \mathsf{E}[\overline{X}^{k}(s)]) \,\mathrm{d}s, \qquad (6)$$

where  $\omega^k$  are independent BM.

## Remarks

- Still nonlinearity at the limit (of McKean-Vlasov type)
- There is invariance in law for all k.
- Given μ<sub>0</sub> the law of X<sup>k</sup>(0), if μ<sub>0</sub> has a finite first moment, (6) becomes equivalent to a linear SDE with an explicit solution (Ornstein-Uhlenbeck process)

DAVYDO\ Michel

Introduction

Well-posedness limit SDEs

Convergence in a toy model

References

### The coupling

We consider the probability space  $\Omega = (\mathbb{R} \times C(\mathbb{R}^+, \mathbb{R}))^{\mathbb{N}}$  endowed with  $(\mu_0 \otimes W)^{\mathbb{N}}$  with the real coordinates being the i.i.d. initial conditions (denoted  $Y^k$  hereafter) and the trajectory coordinates being the i.i.d. Brownian motions (denoted  $B_t^k$ ). We construct on  $\Omega$ the following processes:

• the processes  $(X_t^{k,N})$  verifying

$$X^{k,N}(t) = Y^{k}(0) + B^{k}(t) + \int_{0}^{t} (X^{k,N}(s) - \frac{1}{N} \sum_{j=1}^{N} X^{j,N}(s)) \, \mathrm{d}s \ (7)$$

• the processes  $(\overline{X}_t^k)$  verifiying

$$\overline{X}^{k}(t) = Y^{k}(0) + B^{k}(t) + \int_{0}^{t} (\overline{X}^{k}(s) - \mathsf{E}[\overline{X}^{k}(s)]) \,\mathrm{d}s \qquad (8)$$

DAVYDOV Michel

Introduction

Well-posedness ( limit SDEs

Convergence in a toy model

References

## The convergence theorem

Suppose that  $\mu_0$  has a finite second moment  $\nu_0$ . For all  $1 \le k \le N$ , for all finite T > 0,

$$\sqrt{N} \mathsf{E}[\sup_{t \in [0,T]} |X^{k,N}(t) - \overline{X}^{k}(t)|] \le (\nu_0 + \frac{1}{2}) T e^{2T}.$$
(9)

> DAVYDOV Michel

Introduction

Well-posedness limit SDEs

Convergence in a toy model

References

### Intuition for the proof

Exponential bound: use Gronwall's lemma. Here is a simple version of it (that can be generalized to a much less stringent setting): Let u and b be a nonnegative continuous functions on  $\mathbb{R}^+$ , let a be a nonnegative constant (or nonnegative continuous function). If u verifies the following integral inequality for all  $t \in \mathbb{R}^+$ :

$$u(t) \leq a + \int_0^t b(s)u(s) \,\mathrm{d}s,$$

then

$$u(t) \leq a e^{\int_0^t b(s) \, \mathrm{d}s}$$

▲□▶ ▲□▶ ▲ヨ▶ ▲ヨ▶ ヨー つので

> DAVYDOV Michel

Introduction

Well-posedness limit SDEs

Convergence in a toy model

References

### The proof

By the coupling, we have

$$egin{aligned} X^{k,N}(t) &- \overline{X}^k(t) | \leq \int_0^t |X^{k,N}(s) - \overline{X}^k(s)| + |rac{1}{n} \sum_{j=1}^n (X^{j,N}(s) - \overline{X}^j(s)) \ &+ |rac{1}{n} \sum_{j=1}^n \overline{X}^j(s) - \mathsf{E}[\overline{X}^1(s))]| \, \mathrm{d}s \end{aligned}$$

Let  $\delta(t) = \mathsf{E}[\sup_{t \in [0,T]} |X^{k,N}(t) - \overline{X}^{k}(t)|]$ . Then taking the expectation in the equation above, we have:

$$\delta(t) \leq 2 \int_0^t \delta(s) \, \mathrm{d}s + \int_0^t \mathsf{E}[|\frac{1}{n} \sum_{j=1}^n \overline{X}^j(s) - \mathsf{E}[\overline{X}^1(s))]|] \, \mathrm{d}s$$

> DAVYDOV Michel

Introduction

Well-posedness of limit SDEs

Convergence in a toy model

References

### The proof, continued

Let  $D_N(t) = \mathbb{E}[|\frac{1}{n}\sum_{j=1}^{n}\overline{X}^j(t) - \mathbb{E}[\overline{X}^1(t))]|$ . It is the first moment mean of an empirical mean of centered independent r.v.s. By the Cauchy-Schwarz inequality, we have:

$$D_N(t) \leq rac{1}{\sqrt{n}} \operatorname{var}(\overline{X}^1(t)).$$

Recall that  $\overline{X}^{1}(t)$  is the solution of an SDE with an explicit solution (Ornstein-Uhlenbeck process). Taking the variance in that explicit solution, we show that

$$\operatorname{var}(\overline{X}^1(t)) \leq 
u_0 + rac{1}{2}$$

> DAVYDOV Michel

Introduction

Well-posedness o limit SDEs

Convergence in a toy model

References

## The proof, end

Finally, we have

$$\delta(t) \leq 2\int_0^t \delta(s) \,\mathrm{d}s + \frac{1}{\sqrt{n}}(\nu_0 + \frac{1}{2})t.$$

Applying Gronwall's lemma, the result follows.

DAVYDOV Michel

Introduction

Well-posedness limit SDEs

Convergence in a toy model

References

### Consequence for the convergence

Note that (9) gives a control of the Wasserstein distance between the laws of  $(X_t^{k,N})$  and  $(\overline{X}_t^k)$ . Therefore, for all  $1 \le k \le N$ , for all finite  $t \ge 0$ ,  $\mathcal{L}(X_t^{k,N}) \to \mathcal{L}(\overline{X}_t^k)$  when  $N \to \infty$ .

> DAVYDOV Michel

Introduction

Well-posedness o limit SDEs

Convergence in a toy model

References

#### Remark: stronger result

It is actually possible to prove the convergence of the empirical mean:

$$\frac{1}{N}\sum_{j=1}^N \delta_{X^{j,N}_t} \to \mathcal{L}(\overline{X}^k_t)$$

when  $N \to \infty$ .

## Propagation of chaos

The previous result is usually called *propagation of chaos* because it can be shown that in a certain sense, the asymptotic independence of the N-particle system is equivalent to the weak convergence of the empirical mean.

DAVYDOV Michel

Introduction

Well-posedness c limit SDEs

Convergence in a toy model

References

## Spatial generalizations

• It is possible to introduce a spatial component to the interactions by taking them of the form

$$\frac{1}{N}\sum_{j=1}^{N}K(y_i,y_j)b(X^{k,N}(s),X^{j,N}(s))$$

with  $y_i$  the spatial localization of the *i*-th particle and *K* the kernel of spatial dependence. In this case, you have to consider both the convergence of the processes  $X^{k,N}(s)$  to some limit process and the convergence of  $\frac{1}{n} \sum_{i=1}^{N} \delta_{y_i}$  to a certain limit distribution.

• Another way to preserve the geometry of the *N*-particle system is to consider *replica mean-field* limits, looking at the limit of *M* replicas of the initial particle system with interactions uniformly randomly routed in between the replicas when *M* goes to infinity.

> DAVYDOV Michel

Introduction

Well-posedness limit SDEs Convergence in a toy model

References

Julien Chevallier. "Approximation par champ-moyen : le couplage à la Sznitman pour les nuls". Jan. 2017. URL: https://hal.archives-ouvertes.fr/hal-01433292.

Alain-Sol Sznitman. "Topics in propagation of chaos". In: *Ecole d'Ete de Probabilites de Saint-Flour XIX, vol.1464* (1989), pp. 165–251.